|  | COR REFERENCE <br> IOT U BE AKEN FROM THIS ROOM |
| :---: | :---: |
| RELAXATION MEIHOD | $\frac{1}{4} \tan \cos$ |

A Thesis
Presented to
the Faculty of the Graduate School
Robert College Engineering School

In Partial Fulfillment
of the Requirements for the Degree of
Master of Science
in
Civil Engineering

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by
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## PREFACE

The moments and deflections in a square slab simply supported at the boundaries and on a column at the middle shall be found by the Relaxatio M method. The aim of the thesis will be to find the moments and deflectio in a square three-span slab without drop panels, simply supported at the boundaries and supported on four columns at the interior equidistant from each other.

GENERAL NOTATION
The following notation is used:

```
R1, R2 = Residuals;
\Deltax,\Deltay=Change in the values of }x\mathrm{ and }y
    M = Poisson's ratio, taken as 0.2 (for concrete);
    E = Modulus of elasticity, assumed constant; units of }\textrm{kg}/\mp@subsup{\textrm{cm}}{}{2}
    h = Thickness of the plate, assumed constant; unit of cm.
    M = Summation ofomoments at each mesh point;
MX, My = Moments in x- and y- axes at each mesh point, respectively;
    q = Uniform load on the slab;
    \nabla= The Laplace operator;
\deltaq; \deltac = Deflections due to load and column reaction, respectively;
    K}=-\mp@subsup{\delta}{q}{}/\mp@subsup{\delta}{c}{c}
    w = The variable; !
```

    \(a, b=\) Numberfof mesh divisions of the sides of the slab;
    Myx, Mxy $=$ Torsional moment;
$Q_{x}, Q_{y}=$ Shear in $x$-and $y$-axes, respectively;
$A$ = Distance in direction of span from center of support to the intersection of the center line of the slab thickness with the extreme 45-deg. diagonal line lying wholly within the conorete section of slab and column or other support, including drop panel, capital and bracket.

D = Flexural rigidity of the plate, defined as; units of kg .4 m $D=\frac{E h^{3}}{I 2(1-\mu L)^{\circ}}$
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## BASIC PRINCIPIES

1.1. The Basic Rule of Relaxation. The basic concept of relaxation and its important and widely used modifications can be explained by employing them to solve a pair of algebraic equations, for example:
$3 x+y=50$
$2 x-y=10$
$3 x+y-50=0$
or (1.2)
$2 x-y-10=0$$\quad$ (1.2)

The solution of the problem can be easily verified to be $x=12$ and $y=14$. In order to solve the above equations by 爰 the Relaxation. Metho all the terms shall be written on one side and with only zero on the other side. New quantities called residuals shall be introduced which Will take the place of zero in the above equations. For values of $x$ and $y$ which satisfy the equations (1.2), these residuals are equal to zero. For other values of $x$ and $y$, these residuals will have a value different from zero.
$3 x+y-50=R_{1}$
$2 x-y-10=R_{2}$$\quad(1.3)$

The aim of the relaxation is to make these residuals equal to zero or as small as possible. When this is done $x$ and $y$ will automatically setisfy the above equations.

The process of solution is started by the selection of an initial pair of values for $x$ and $y$ equal to zero. Then for the above equations (1.3), $R_{1}=-50$ and $R_{\mathscr{2}}=-10$. Now if we change $x$ by $I$ unit, $R_{1}$ is changed by three units while R2 is changed by 2 units, if on the other hand we differ $y$ by 1 unit, $R_{1}$ is increased by 1 unit, and Rzis decreased iby l unit. This can be put in tabular form called the "Operations Table" THE OPERATIONS TABI妇 QNE

|  | $\Delta=R_{1}$ | $\Delta=R_{2}$ |
| :---: | :---: | :---: |
| $\Delta x=1$ | 3 | 2 |
| $\Delta y=1$ | 1 | -1 |

The process of relaxation consists of the application of the unit opera tions repeatedly, gradually, to change residuala from their initial value to zero. The first step in the relaxation will be to change the largest residual, in this case $\mathrm{R}_{1}=-50$ approximately to zero, i.e., by a change of +50. Prom the operations table $x=50 / 3$ or about 15. This operation change the value of $-\mathrm{R}_{2}$ to +20 . This can be repeated until we obtain zero or close to zero values for our residuals. The total process written in tabr lar form is as follows:

OPERATIONS TABTE TWO

| $x$ | $y$ | $R_{1}$ | $R_{2}$ |
| :---: | :---: | :---: | :---: |
| 0 | 0 | -50 | -10 |
| $\Delta_{x=15}$ | 0 | -5 | +20 |
| $\Delta_{y}=-2$ | $\Delta_{y}=10$ | +5 | +10 |
| $\Delta_{x}=-1$ | 4 | -13 | +6 |
| $x=12$ | $y=14$ | 0 | 0 |

The final ilne in this table both summarizes and checks the calculation In the first column; the solution to the problem is recorded by summing for each unknown the value initially assigned and all increments added th it subsequently,e.g. $x=0$ (initially) $+15-2-1=12$. The last ine is aimply check, it is derived by substituting the falues of $x$ and $y$ in the equatr 1ons (1.2).
1.2. Block Relaxation. Block relaxation consists in the use of operations other than the basic unit operations. They entail the simultaneou: application of increments to more than one of the unknowns at the same $t$ In the example of article (1.1) the block unit operation would be $\Delta_{\mathrm{x}}=\Delta_{\mathrm{y}}=$ In this case the operations table is:

OPERATIONS TABIE THREE

|  | $\Delta R_{1}$ | $\Delta R_{2}$ |
| :--- | :--- | :---: |
| $\Delta x=1$ | 3 | 2 |
| $\Delta y=1$ | 1 | -1 |
| $\Delta x= \pm y=1$ | 4 | 1 |

The total residual is -60 . The unit block operetion affects a change of $4+1=5$. So, as a first step we shall take a block operation
$\Delta x=\Delta y=\frac{-(-60)}{5}=12$.
OPERATIONS TABIE FOUR

| $X$ | $y$ | $\Delta R 1$ | $\Delta R 2$ |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 650 | -10 |
| $\Delta x=12$ | $\Delta x=12$ | -2 | 2 |
|  | $\Delta y=12$ | 0 | 0 |
| $x=12$ | $y=14$ | 0 | 0 |

The table shows the usefulness of block relaxation as less steps are involved. There are ather devices such as group relaxation, over-relaxat used but we are not directly concerned with them though the reader is ceferred to books on Relaxation Methods.

The simultaneous equations solved above are examples that show the advantage of the method. It is inefficient to solve two simultaneous equations by this method but if there are too many unknowns invorved, the advantage of the method can be clearly seen. The most important applicat of the relaxation method has been to obtain particular solutions of parti differential equations in two dimensions.

In this thesis the method has been used in solving the partial differer tialequations encountered in the theory of thin plates. In any applicati of the relaxation method for the solution of a differential equation, finite difference approximations have to be used. It is by solving these finite difference equations that we shall have a solution of the wanted function at a number of equelly spaced points.

The relaxation method is a numerical method of solution that has been developed in recent years mainly by $R_{0}$. $V$. Southwell.

## GENERAL THEORY

2.1. The Differential Equation of a Thin Plate. The differential equation of a thin plate loaded laterally with a uniform load of $q$ is

$$
\begin{equation*}
\frac{\partial^{4} w}{\partial x^{4}}+\frac{2 \partial^{4} w}{\partial x^{2} \partial \bar{y}^{2}}+\frac{\partial 4 w}{\partial y^{4}}=\frac{q}{D} \tag{2.1}
\end{equation*}
$$

where

$$
D=\frac{E h^{3}}{12(1-\mu)^{\prime}}, \text { the finexural rigidity of a plate. }
$$

$\mu=$ Poisson's ratio.
$E=$ Modulus of elasticity.
$\mathrm{h}=$ The thickness of the plate.
The above fourth order partial differential equation can be put into two second order Poisson type differential equations. Thus reducing considerably the work involved in the solution of Eq. (2.1)., especially when difference equationscareased.

$$
\begin{align*}
& \left.\frac{(\partial 2)}{\partial x^{2}}+\frac{\partial L}{\partial y^{2}}\right)\left(\frac{\partial^{2}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}\right)=\frac{q}{D}  \tag{2.2}\\
& M_{X}+M_{y}=-D(1+\mu)\left(\frac{\partial L_{w}}{\partial x^{2}}+\frac{\partial 2_{w}}{\partial y^{2}}\right) \tag{2,3}
\end{align*}
$$

but

$$
\begin{equation*}
M=\frac{M x+M y}{1+M}=-D\left(\frac{\partial z_{w}}{\partial x^{2}}+\frac{\partial^{2} w}{\partial y^{2}}\right) \tag{2.4}
\end{equation*}
$$

putting

Equation (2.1) can be written as

$$
\left(\frac{\partial z}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{z}}\right)(M)=-q
$$

$$
\begin{equation*}
\left(\frac{\partial^{2} M}{\partial x^{2}}+\frac{\partial^{2} M}{\partial y^{2}}=-q\right. \tag{2.5a}
\end{equation*}
$$

$$
\begin{equation*}
\left(\frac{\partial 2_{w}}{\partial x^{2}}+\frac{\partial 2_{w}}{\partial y^{2}}\right)=-\frac{M}{D} \tag{2.5b}
\end{equation*}
$$

In the case of a simply supported rectangular slab the boundary conditions for equations (2.5a) and (2.5b) are $w=0$, and $\frac{\partial w^{w}}{\partial x^{2}}, \frac{\partial^{2} w}{\partial y^{2}}$ are equel to zero, which makes $M=0$.
2.2. Finite Difference Approximations. In any application of the relaxation method to solve a differential equation, certain finite difference approximations of derivatives have to be used, and we shall establish two of these approximations which will be needed in this chapl

Suffixes as in (Fig. 2.1) are used to show a typical point of subdivision when working out a general result.


Fig. 2.1. Corresponding suffixes are used to indicatecvalues of the function $W$, the transverse deflection, in an expansion of the Taylor series: $w=w e+\left(\frac{d w}{(X X}\right)_{e}\left(x-x_{e}\right)+\frac{1}{2}\left(\frac{\left.d^{2} W_{N}\right)}{\left.d x^{2}\right)_{e}}\left(x-x_{\theta}\right)^{2}+\frac{1}{3}\left(\frac{\left.d^{3} W_{w}\right)}{\left.d x^{3}\right)_{e}}\left(x-x_{e}\right)^{3}+\ldots\right.\right.$ In this relation, if $x$ is put equal, in turn, to ( $x e+h$ ) and ( $x e-h$ ), we find that,
$w f^{=} W_{e}+h\left(\frac{d w}{(d x}\right)_{e}+\frac{h 2}{2}\left(\frac{d^{2} w}{\left(d x^{2}\right)_{e}}+\frac{h^{3}}{6}\left(\frac{d^{3} w}{\left(d x^{3}\right)_{e}}+\frac{h^{4}}{24}\left(\frac{d^{4} w}{\left(d x^{4}\right)_{e}}+. .\right.\right.\right.$.
$w d=w e-h\left(\frac{d w}{\left(\frac{d}{x}\right)_{e}}+\frac{h^{2}}{2}\left(\frac{d^{2} w}{d x^{2}}\right)_{e}+\frac{h^{3}}{6}\left(\frac{d^{3} w}{d x^{3}}\right)_{e}+\frac{h^{4}}{24}\left(\frac{d^{4} w_{J}}{\left(\frac{d x^{4}}{}\right)_{e}}+. .\right.\right.$.
Adding these two results together, we get
$W f^{+}+d^{m 2} W_{e}+h^{2}\left(\frac{d^{2}}{d x^{2}}\right)_{e}+o\left(h^{4}\right)$.
where all the terms containing fourth of higher powers of $h$ are included together as $O\left(h^{4}\right)$. Neglecting this quantity as $h$ is made smaller and smaller, we have the finite-difference approximation to $\left(\frac{d^{2} w}{\left(x^{2}\right)_{e}}\right.$ :

$$
\begin{equation*}
h^{2}\left(\frac{d^{2}}{\left(x^{2}\right)}\right)_{e}=w_{f}+w_{d}-2 w_{\theta} \tag{2.6}
\end{equation*}
$$

In two dimensions as in one, the relaxation solution to a differential equation consists of a finite number of values of the wanted quantity w at a number of points within the region of integration. Whereas in one dimension a range of integration was divided up by points of subdivision into a number of equal intervals, in two dimensions an area of integration is subdivided by a uniform network, and the values of w are calculated at the nodes of the network. Such networks are known as relaxation nets, the commonly used one is thelsquare net, rarely the triangular net is used.

An ordinary differential equation; also any partial differential equation has to be replaced by a set of finite difference equations. For Poisson's equations this can be easily done since it involves only
se of the approximation for a second derivative. imensions to denote a typical node "e "and the urrounding nodes.

$$
h^{2}\left(\frac{\partial 2_{w}}{\partial \bar{X}^{2}}\right)_{e}=w f^{+w d-2 w e} \quad(2.7 a)
$$

as the finite-difference approximation for the recond derivative of $w$ at the point " $\theta$ ", on the $x$ axis. In the same jay it may be shown that, for the second derivative with respect to $y$, ihe approximation is

$$
h^{2}\left(\frac{\partial 2_{W}}{\left.\partial y^{2}\right)_{E}}=W_{b}+w j-2 W_{e} \quad(2.7 b)\right.
$$

ldding (2.7a) and (2.7b) together, we obtain the finite-difference approximation for $\nabla^{2}$ at a typical node (node e).

$$
\begin{aligned}
& h 2\left(\nabla^{2} w_{e}=w_{f}+w_{b}+w_{d}+w_{j}-4 w_{e}\right. \\
& w_{f}+w_{b}+w_{d}+w_{j}-4 w_{e}-h^{2}\left(\nabla^{2} w_{e}\right)_{e}=0
\end{aligned}
$$

Phere is again an error of $0 \operatorname{lnh}^{4}$ ) in this equation, and the effect of this orror again diminishes with the mesh size $h$. Equation (2.8) must be satisfied by the wanted value of $w$ at every group of five nodes. For any othervallue of $w$ the above equation won't be satisfied and thus a residual ( R ) will resuat. Putting Eq. (2.8) in the form below,

$$
w j^{+w \rho}+w_{b}+w d-4 w_{e}-h^{2}\left(\nabla^{2}{ }_{w}\right)_{\theta}=R_{e} \quad \text { (2.9) }
$$

we should try to reduce each $R_{e}$ to a value which will be zero or very close to it by the application of increments $w$. Examining Eq. (2.9), if wj is altered by +1 , Re is altered by +1 , and similarly for unit alterations to $\mathrm{w}_{\mathrm{f}}, \mathrm{wb}_{\mathrm{b}}, \mathrm{w}_{\mathrm{d}}$. If, wowever, $\mathrm{we}_{\mathrm{e}}$ is altered by +1 , then $R_{e}$ is altered by -4 . The alterations of the residuals thus follows a


Fig. 2.3. definite pattern, and the residuals can be systematically reduced. The amount of work in oalculating and ohanging the residuals can be reduced to some extent by the use of the so called "Relaxation Operator." The relaxation operator is $\dot{A}$ a diagramatical form of the finite-difference
quation. The relaxation operator of the present problem is that shown In (Fig. 2.3). Remembering the relaxation operator, the residuals at each point can be computed easily. At the same time, the changing of the cesiduals is made easier because the operator indicates that a change of the value $w$ at the center point by +1 changes the residual at the center point by -4 and the residuals at each of the four surrounding points by +

If we were to put Eq. (2.1) into finite-difference form, the required form would be,

$$
20 w_{e}-8\left(w_{b}+w d+w_{f}+w_{j}\right)+2\left(w_{0}+w_{m}+w_{r}+w_{p}\right)+\left(w_{s}+w_{r}+w_{t}+w_{u}\right)=h^{4} q / D \quad(2.10)
$$

Below is the (Fig. 2.4) that shows the lettered nodes and (Fig. 2.5) is the relaration operator of Eq. (2.10). It is obvious that Eq. (2.10) is a much more complicated form to deal with than the equivalent finite difference forms of Eqs. (2.5a) and (2.5b).


To get the same result as Eq. (2.10) we have to relax Eq. (2.5a) by putin the q-values at the nodal points and as a result the sum of moments are obtained at the same points. Then Eq. (2.5b) is relaxed by putting the sum of moments as loads at the nodal points until the residuals are minimized. Henceforth the relazation of Eq. (2.5a) shall be called the M-relaxation and the relaxation of Eq. (2.5b) the w-relaxation which will give the value of the deflection ratherw(p)at each nodal point.

CHAPTER 3
THE ANAIYSIS OF A SQUARE SIAB WITH A COLUMN AT ITS CENTER The main purpose of this thesis is to find the moments in a three spar slab without drop panels, simply supported at the boundaries and support on four column at the interior equidistant from each other, and compare the moments with those of the ACI code.

As an introduction a problem of this sort shall be solved. A slab wil be taken with a column supporting the slab in the middle. To find the column reaction and its effects, the slab without a column is analyzed and the deflections in the middle are found due to the loads. This deflection shall be called $\delta q$. Then a unit load will be placed at the middle where the colurm is and the deflections $\delta_{c}$ will be found. The column reaction will be,

$$
\begin{equation*}
K=-\frac{\delta_{q}}{\delta_{c}} \tag{3.1}
\end{equation*}
$$

The deflection at any node is equal to the deflection of the load+(algeb raically) the deflection due to the reaction at that point. A square slab of 4 m . by 4 m . will be taken loaded with a uniformly distributed 108 of say $1000 \mathrm{~kg} . / \mathrm{m}^{2}$. The slab shall be sliced into four equidistant stri with mesh points lm, from each other. The load per mesh point will be $1000 \mathrm{~kg} . / \mathrm{m}^{2}$. (1m.) (1m.) $=1000^{\text {kjand }}$ it shall be placed at each mesh point for relaxation.

In this example the Point Relaxation method is applied, that is to say a unit change in the variable $w$, will change the residual at each point under consideration by a -4 and the surrounding points by +1 according to the relaxation operator (Fig. 2.3). The resuat of this relaxation gives the sum of moments at each nodal point according to equation (2.5 By taking these as loads at each nodal point and using point relaxation the deflections of each point are obtained. The moments and shears at each point can be found whan the deflections values at the same points are known.
3.1. Relaxation Method. Now let us start the relaxation process at the conter point and reduce the residual there to zero. Thus we have to add $+1000 / 4$ or +250 at that point. With this alteration of the vari-
 by an amount of +250 . Record the final values of the residuals at the rightforner of each nodal point and the change in w, the variable at the left upper corner. This is shown as step 2 in (Fig. 3.2). The nodal points ander consideration shall be numbered as shown in (Fig. 3.1).


Fig. 3.1. The method of numbering adopted is used througout on books of relaxation methods.

The residual at point 1 which has become 1250 will be reduced. To reduce it to a value near zero, we shall add a value of $+1250 / 4$ or about 300 at this point. Thus the residual at 1 becomes +50 , and the residuals at its surrounding points are shown as step 3 in (Fig. 3.2). Point 3 is a boundary point, and the value of the function at this point is determinde by the boundary conditions. As the boundary condition is satisfied, the residual there is zero. It is observed that by reducing the residual at 1 , the residual at point 0 is again increased. To reduc this additional residual we must increase wo again. This always happen whan a point is surrounded by other points with residuals of the same sign. To make the convergence more rapid, instead of reducing Ro in st 2 to zero we may increase $w_{0}$ in step 2 so that Ro becomes a negative value. This process is called over-relaxation. The amount of over-rel ation depends on the magnitudes of residuals at the surrounding points. By not overssooting enough or by overshooting too much no harm is done except that some time is lost. Now both points 2 at the right side of the vertical center line have residuals of 1300. To reduce them, let u over-relax the residuals by adding 600 at both points. The changes in


Step 2


Step 6


Step 7


Step 8

Fig. 3.2. M-relaxation of uniform load on square-slab.
the residuals and the values of $w$ are shown as step 4. Next we add 800 to point above and below 0 , respectivelly. The results are shown as step 5. Now, 800 shall be added at point 0 and $1 ; 600$ at points 2 of the left side of the vertical center line and 500 at point 1 . The final residuals are shown as step 6. The residuals have now been reduced to a maximum value of 200. If we add 80 at all the inner points, the residuals shall be considerably reduced. The final residuals are shown as step 7 . Some further changes as in step 8 reduces the residuals to a minimum.
*3.2. Block Relaxation and Lines of Symmetry. Thefprocedure of
*. T. Wang, Applied Elasticity. (New York: Mc. Graw Hill Book Co. Inc., 1953), p. 119.
relazation may be altered by the computer for a rapid approach to the final answer of no residuals. We shall now discuss a few short cuts in the relaxation technique which will serve to accelerate the elimination of the residuals.

One of these relaxation techniques is the so-called line and block relaxation. In step 7 of the example considered in Sec. 3.1, we found that the residuals could be reduced by adding 80 to the values of $w$, at all the net points. Altering simultaneousiy all the values of the function by the same amount at a group of points in a block of the domain is called block relaxation. Similarly, simultaneously altering the values of the function by the same amount at a group of points along a line in the domain is called line relaxation.

Consider the effect of the simultaneous chaging of the function of two adjacent points by the same amount. Obviously this may be carried out by writing down seperately the effects of each displacement and adding them together: In the case of the Iaplace operator, by the use of unit opera? tors, we can obtain the two-, three-, and four-point line-relaxation operators, as shown in (Fig. 3.3), and the various block-relaxation operat


Fig. 3.3. Two-, Three-, and Four-Point Line-Relaxation Operators,


Fig.3.4. Block Relaxation Operators.


Fig. 3.5. Block Relaxation Operator
as shown in (Figs. 3.4 and 3.5). Inspecting the operators as shown in (Figs. 3.3, 3.4, and 3.5) carefuliy, we find that it is possible to obtain a rule by which all such operators can be inmediately written down by inspection. The rule for writing the line- and block-relaxation operators for Laplace or Poisson's equations is as follows. By simultaneously altering the values of the function at a group of points in a region along a line or within a block by an amount of +1 , the residuals at all points whith, like a (Figs. 3.3. and 3.4), are directly connected with three points outside the line- or block-relaxation region are altered by an amount of -3 . The residuals at all points which, like $\underline{b}$, are connected with two outside points, are altered by an amount of -2. The residual at a point such as $\mathbf{c}$ is altered by an amount of -1 when the point is connected with one outside point. There are no changes in the residuals at points such as $\underline{\alpha}$ which are not directly connected with any outside points. The residuals at all points e, which are outside the line- or block-relaxation region but directly connected to one point within the region, are altered by +1 . The residual at an outside point such as $\pm$ which is directly connected to two outside points is altered by +2. The advantage of the line and block relaxation can easily be seen from (Fig. 3.5). For while the residuals at the points on the boundary of the block are altered, the residuals at points inside the blook are not changed. Judicious use of block relaxation can prevent much of the "washing back" of residuals, thus saving much time in obtaining a solution.

Another useful relaxation technique is the observation of the lines of symmetry. In many problems the solution can easily seen to be symmetrical with respect to one or more $\exists$ ines because of the symmetry of the domain and boundary conditions. In solving such problems, it is unnecessary to find the unknown function over the entire area. In the example of Sec. 3.1 , there is an eightfold symmetry. Thus it is sufficen tofind a solution in one-eight of the domain, as shown in (Fig. 3.6).

There is no markedly new technique involved in solving such problems. It is merely necessary to remember that to priserve symmetry each time a point adjasent to a line of symmetry is altered the point which is symmetrical to this point is altered at the same time. That is, such an operation is accompaniedby an automatically equal change on the other side of the line of symmetry. As a result, a point on the line of symmetry will receive a change in its residual from both of the points being altered.

In the problem of Sec. 3.1, in (Fig. 3.2), the computation was deiberately lengthened by ignoring the symetrical property of the solution. Dusing the relaxation process, the computations should be checked from time to time by evaluating the residuals at all the nodal points. If there are mistakes it is advisable to correct the residuals at the nodal points by using Eq. (2.9). As far as the thesis is concerned, the M- relazation is accomplished. The w-relaxation can be done by using line relaxation. The numbering of the nodal points will be as in (Fig. 3.1), the center point is 0 , the side points as 1 , and the corner points as 2. The corresponding change of a variable of +1 put at any one of the three nodal points will be illustrated with the following three diagrams of relaxation operators. The numbering of the points will be written on the lower left corners of each point througout this paper.


Fig. 3.6. The steps are not written one by one but the relaxation is carried out on page 18. The 1035 middle deflection can be compared with the result of a similar slab solved by elasticity such that

$$
\text { (D) } \mathrm{w}_{\max }=0.00406 \mathrm{qa} a^{4}=0.00406(1000)\left(4^{4}\right)=1040
$$

The exact and approximate results are in good proximity.


Fig. 3.7. $v$-relaxation of uniformly distributed load on square-slab simply supported at the boundario.

The above found values at the nodal points are the deflections of each point due to the uniformly distributed lea To find the column reaction a load of 1000 kg shall be at point 0 for relaxation. The deflections introduced : the column load at 0 will have the opposite sign to deflections of the uniformly distributed load.

Next, the lad on the colum, suppating the slab tron middle, shall be found.


Fig. 3.8. M-reis. tron of column load. at 0 .


Fig.3.9. w-relaxation of column load at 0 .

$$
\begin{aligned}
K \cdot 220 & =1035 \\
K & =4.71
\end{aligned}
$$

Therefore the column reaction is 4710 kg . The final deflection with a column reaction acting are as follows.

$$
\begin{aligned}
& \omega_{2}=549-4.71 \times 79=549-372=177 \mathrm{~cm} \\
& \omega_{1}=753-4.71 \times 126=753-594=159 \\
& \omega_{0}=1035-4.71 \times 220=1035-1035=0
\end{aligned}
$$

The results of the examples solved in Secs. 3.1 and 3.2can be increased In accuracy if the slab is divided into eight meshes. . The same process of relaxations shall be done again. The load per mesh point will be $1000 \mathrm{~kg} . / \mathrm{m}^{2} .(0.5 \mathrm{~m}).(0.5 \mathrm{~m})=.250 \mathrm{~kg}$. and it shall be placed at each mesh or nodal point for relaxation. The relaxation operators for the 8 mesh model are shown on page 21 in (Fig. 3.10). The relaxation of the aniform load is performed in two steps. First block relaxation shall be used and the approximate residuals will be carried further by point relaxation. The block relaxation portion of the job is shown in (Fig. 3.1.1) and the further point relaxation in (Fig. 3.12). Note that block relaxation is carried from the outskirts of the slab to the center in (Fig. 3.11). The 438 kg . of step 1 is found as:
$1000 \mathrm{kgi} / \mathrm{m}_{2}^{2}(0.5 \mathrm{~m}),(0.5 \mathrm{~m}),(\mathrm{No}$, of mesh points $)=\frac{250 \mathrm{~kg},(49)}{28}=438 \mathrm{~kg}$. load per node point ( $n-1$ ) (3.2)
where $n=n o$. of division of meshes of a square slab. For any kind of rectangular slab the general formula is:

$$
\frac{\text { 1oad per node point }(\mathrm{a}-1)(\mathrm{b}-1)}{2(\mathrm{a}+\mathrm{b}-2)}
$$

where ann. of mesh divisions of one side of the slab;
$b=n o$. of mesh divisions of the other side of the slab;


The Relaxation Operators for the 8 mesh motel:

$1:$

$$
=\frac{1000 \times 05^{2} \times 49}{28}=433 \mathrm{~kg} .
$$



Ep $3:$

$$
=\frac{250 \times 9}{12}=188 \mathrm{~kg} .
$$



Stcp 2:

$$
=\frac{250 \times 25}{20}=312 \mathrm{~kg} .
$$



Step 4:

$$
=\frac{250 \times 1}{4}=62 \mathrm{~kg} .
$$

Fig. S.t1. Blouk reluaticn of uniformby diatributed lobl st A-mesh syute-sha surply supported at the


Fig. 3.12. M -relaxation of uniform load on square ahab ।
Above, the residuals and the variables of the black Relaxation are carried by point relaxation.

The above relauqtion resits should be multiplied
by $h^{2}$ so as to find the deflections by the wrelaxation, where $A$ the space length beturen miosis lines. It will be cumbersome to do this every tin a for each slab instead the Mr and My moments shat be matiolied by $h^{2}$
$-24-$


Fig. 913. W-relaxation of uniform lode d on square slab.



Fig. 3.15. W-relaxation of column load at 0 of squer slab simpiy supportal at the bouncuros

$$
K=\frac{4156}{807}=5.15
$$

The colum reaction is $=5.15(1000)=5150 \mathrm{~kg}$.
The deflections of the colum load are opposite in sign to the deflections of the uniformly distributed load. The final deflections, 1.e. (w) ( $D$ ) 's with a column reaction acting are assfollows:

```
Wg= 680-5.15( 88)=680-453=227 cm.
W8}=1217-5.15(166)=1217-855=362 cm.
W
w6
W5=2189-5.15(317)=2189-1633=556 "
w4=2803-5.15(433)=2803-2230=573 . i
W3=3012-5.15(481)=3012-2477=535 ,
w
W1=3865-5%i 15 (684)=3865-3523=342 . "
WO}=4156-5.15(807)=4156-4156=0
```

The moments $M_{x}$ and $M y$ at each nodal point are found by the following formulas:

$$
\begin{align*}
& M_{X}=D\left(\frac{\partial^{2} w^{\prime}}{\partial x^{2}}+\frac{\mu \partial z_{W}}{\partial y^{2}}\right)  \tag{3.4}\\
& M_{Y}=D\left(\frac{\mu}{\partial \partial_{W}}+\frac{\partial z_{w}}{\partial y^{2}}\right) \tag{3.5}
\end{align*}
$$

The torsional moments are:

$$
\begin{equation*}
M_{y x}=M_{x y}=D(1-\mu) \frac{\partial 2_{w}}{\partial x \partial y} \tag{3.6}
\end{equation*}
$$

where $\mu=0.2$
The shear Qx and Qy are:

$$
\begin{align*}
Q_{x} & =\frac{\partial M_{x}}{\partial x}-\frac{\partial M_{x y}}{\partial y}=-\frac{\partial}{\partial x}\left[D\left(\frac{\partial 2_{w}}{\partial x^{2}}+\mu \frac{\partial z_{w}}{\partial y^{2}}\right]-\frac{\partial}{\partial y} D(1-\mu) \frac{\partial^{2}}{\partial x \partial y}\right. \\
& =-D \frac{\partial}{\partial x}\left(\frac{\partial 2_{w}}{\partial x^{2}}+\frac{\partial^{2}}{\partial y^{2}}\right) \\
Q_{y} & =\frac{\partial M_{x}}{\partial y}-\frac{\partial M_{x y}}{\partial x}=-\frac{\partial}{\partial y}\left[D\left(\frac{\partial 2_{w}}{\partial y^{2}}+\frac{\partial 2_{W}}{x^{2}}\right)\right]-\frac{\partial}{\partial x} D(1-\mu) \frac{\partial^{2} w}{\partial x \partial y} \\
& =-D \frac{\partial}{\partial y}\left(\frac{\partial 2_{w}}{\partial x^{2}}+\frac{\partial 2_{w}}{\partial y^{2}}\right) \tag{3.8}
\end{align*}
$$

The finite difference form of the equations (3.4) and $\$ 3.5$ ), where "e" in (Fig. 2.2) will be a typical node with the surrounding nodes b, d, f,j.

$$
\begin{align*}
& \left.\frac{M_{D}}{D}=\frac{\left(2 W_{e}-W_{0}-W_{I}\right)}{h^{2}}\right)+\mu\left(\frac{2 W_{e}-W_{B}-W_{H} t}{h^{2}}\right)  \tag{3.9}\\
& \left.\frac{M_{x}}{D}=\mu\left(\frac{\left.2 W_{e}-W_{d}-W_{f}\right)}{h^{2}}\right)+\frac{\left(2 W_{e}-W_{10}-W_{f} f\right.}{h^{2}}\right) \tag{3.10}
\end{align*}
$$

as all the w's are actually w.(D), the modified $M x$ and $M y$ moments after multiplying by hehas noted on p. 23, will be:
$M_{X X}=\left(2 w_{e}-w_{d}-W_{f}\right)+\mu_{\left(2 w_{e}-w_{b}-w_{j}\right)}$
$M_{y}=\mu\left(2 w_{e}-w d-w f\right)+\left(2 w_{e}-w_{b}-w_{j}\right)$
Now the moments of the 8 mesh model will be found.

| $M_{X 9}=2(227)-362$ | $+0.2[2(227)-362]=110$ | $\mathrm{kg}-\mathrm{m} / \mathrm{m}$ |
| :---: | :---: | :---: |
| $M_{X 8}=2(362)-556$ | $+0.2[2(362)-227-401]=187$ | 11 |
| $M_{177}=2(401)-573$ | $+0.2[2(401)-396-362]=238$ | 1 |
| $M_{46}=2(396)-535$ | $+0.2[2(396)-2(401)]=255$ | " |
| $M_{x 5}=2(556)-573$ | $2+0.2[2(556)-573-362]=212$ | " |
| $M_{14}=2(573)-401-4$ | $0+0.2[2(573)-535-556]=266$ | 1 |
| $\mathrm{M}_{\mathbf{X} 3}=$ ( 535 )-342-3 | $6+0.2[2(535)-2(573)]=317$ | " |
| $M_{\times 2}=2(490)-573-3$ | $2+0.2[2(490)-573-342]=78$ | " |
| M ${ }^{\text {x }}=2(342)-535-0$ | $+0.2[2(342)-2(490)]=90$ | " |
| $\mathrm{MxO}_{\mathrm{O}}=2(0)-2(342)$ | $+0.2[2(0)-2(342)]=-821$ | 4 |


My8 $=96+0.2(168)=130$
"
$M_{y 7}=44+0.2(229)=90 \quad 1$
$\mathrm{My}_{6}=-10+0.2(257)=41 \quad "$
My5= ----------- $=212 \quad "$
My $4=55+0.2(255)=106$
My $3=-76+0.2(332)=-12$
My2=----------- 72
My $1=-296+0.2(149)=-266 \quad 1$


CHAPIER 4
THE ANAIYSIS OF A SIMPIY SUPPORTED SIAB WIIH FOUR SYMMETRICAITY PIACED COLUMNS

In the first part of the thesis a slab was solved simply supported at the boundaries and on a column at the middie. For this slab the deflections and moments were found only for the eight mesh model and the deflections for the four mesh one. The aim of the thesis is to collect interest on a slab simply supponted at the boundaries and supported internally on four colums equiditant from each other and the boundaries. The slab to be investigated has dimensions of 4 m . by 4m. : The relaxation procedure will be similar to the previous ones. The uniform loading will be $1000 \mathrm{~kg} . / \mathrm{m}^{2},(4 / 6 \mathrm{~m}).(4 / 6 \mathrm{~m})=.445 \mathrm{~kg}$. for the M-relaxation of the uniform load. The relaxation operators for the 6 mesh model are shown in (Fig. 3.16) with the lines of symmetry indicated. The operations tables follow.


The Relaxation Operators for the Gi men model:



Fig. 4.2. M-relaxation of the unitom loat?


Fig. to, 1 - whation et tive wntam 'cuc'

a

Fig. $4 i$ M-ralaxation of column loud at $\alpha$.


Fig ts. w-rclaxation of column lead at e

It is sufficient to find the load on one column as all four of them are similarly loaded.

$$
K=\frac{1797}{906}=1.985
$$

The column reaction is $=1.985(1000)=1985 \mathrm{~kg}$. The final deflections at the mesh points are:

$$
\begin{aligned}
& W_{5}=6421.9885(281)=642-558=84 \\
& w_{4}=1071-1.985(500)=1071-993=78 \\
& w_{3}=1219-1.985(563)=1219-1118=101 \\
& w_{2}=1797-1.985(906)=1797-1797=0 \\
& W_{1}=2049-1.985(1000)=2049-1985=64 \\
& W_{0}=2338-1.985(1125)=2338-2232=106
\end{aligned}
$$

In the previous example, it was not necessary to find the moments since another square slab having dimensions 6 m . by 6 m . shall be analyzed with the same given conditions but this time the slab shall be divided into 12 meshes so as to minimize the error of the deflections and the moments to be found. To find the moments, strips shall be considered such as the column strip, the middle strip as is done in the analysis of flat slabs in reinforced concrete. This so called strip analysis couldn't be done with the 6 mesh model as there were insufficient nodal points and therefore insufficient deflections. The previous example was done so that it would be a useful guide to the 12 meshed example. In this example the load per nodal point will be $1000 \mathrm{~kg} \cdot / \mathrm{m}^{2} .(0.5 \mathrm{~m}).(0.5 \mathrm{~m})=.250 \mathrm{~kg}$. Block relaxation shall be followed by point relaxation. Under each Fig. is written what that Fig. is about so as to facilitate the reading of the thesis.
stepl:


5top 3:

$$
=\frac{250 \times 7 \times 7}{4 \times 7}=38 \mathrm{~kg} .
$$

STEF $4:$

$$
=\frac{252 \times 5 \times 5}{4 \times 5}=31 \mathrm{kkg} .
$$



Fi3. 46. Blowe relaxation of the uniform load en the square-slab.

3ヶ, :

$$
=\frac{a^{2} 00 x}{7 x-}=189 \mathrm{~kg}
$$

$$
=\frac{\operatorname{tex} 16}{1 \times 4}=4
$$



Fig. it. Block relaxation of the writorm laxd er ita syucare slab.


The Relaxation Operators of the 12 maw, mores


Fig. 4.8


Fig.t.\% The relakution oporutors of the 12 mesh model (womtinued from p.36).



Fig. 4.10. The relaxation operators of the 12 mesh model.


Fig. 4.11 M-relaxation of uniform load on square slat


Fig. 4.12 w-relaxation of uniform load on square slab


Fig. 413 M-relaxation of column load at $j$. The column load is 1000 kg .


Fig. 4.14 w-relaxation of column load at $j$

The column reaction is $=1000(4,609)=4609 \mathrm{~kg}$.. As the other columns bear the same load, the true deflections at the mesh points are:

```
wa}=1600-4.609(294)=1600-1355=245 cm.
wb}=3024-4.609(572)=3024-2636=388 \।
\mp@subsup{w}{C}{}}=5734-4.609(1115)=5734-5139=595 и.
wd}=4186-4.609(815)=4186-3756=430 _
w
w f}=11061-4.609(2284)=11061-10527=534 | |
wg}=5040-4.609(1000)=5040-4609=431 
wh}=9594-4.609(1957)=9594-9020=574 il. 
wi}=13356-4.609(2818)=13356-12988=368 |, 
w j=16144-4.609(3503)=16144-16144=0
w
W W = 10593-4.609(2165)=10593-9979=614 #
Wm}=14759-4.609(3099)=14759-14283=476 ". 
Wn=17851-4.609(3818)=17851-17597=254 _
wo =19746-4.609(4209)=19746-19399=347 ו".
wp}=5735-4.609(1145)=5735-5277=458 |.
wq}=10929-4.609(2231)=10929-10283=646 |।.
Wr
W
W
wu=21043-4.609(4463)=21043-21570=473 ")
```

The $M x$ moments at the mesh points are:

$$
\begin{aligned}
& M_{\text {xa }}=2(245)-390 \quad+0.2[2(245)-390]=120 \quad \mathrm{~kg}-\mathrm{m} / \mathrm{m} . \\
& \mathrm{M}_{\mathrm{xb}}=2(388)-595+0.2[2(388)-245-430]=201 \quad \text { " } \\
& M_{X 0}=2(595)-388-618+0.2[2(595)-388-618]=221 \quad \text { " } \\
& M_{X d}=2(430)-618 \quad+0.2[2(430)-388-431]=250 \quad \text { " } \\
& M_{\text {Xe }}=2(618)=430-534+0.2[2(618)-595-574]=286 \\
& M_{X f}=2(534)-618-368+0.2[2(534)-618-368]=98 \quad \text { " } \\
& M_{x g}=2(431)-574 \quad+0.2[2(431)-430-449]=285 \quad \text { " } \\
& \mathrm{M}_{\mathrm{xh}}=2(574)-431-368+0.2[2(574)-618-614]=332 \quad \text { " } \\
& M_{X i}=2(368)-574 \quad+0.2[2(368)-534-476]=99 \quad \text { " } \\
& M_{X j}=0 \quad-368-254+0.2[2(0)-368-254]=-746 \\
& \mathrm{Mxk}^{2}=2(449)-611+0.2[2(449)-431-458]=286 \\
& M_{x l}=2(614)-449-476+0.2[2(614)-574-646]=305 \\
& M_{\mathrm{xm}}=2(476)-614-254+0.2[2(476)-368-551]=91 \\
& \mathrm{M}_{\mathrm{Xn}}=2(254)-476-347+0.2[2(254)-0-385]=-290 \\
& M_{x 0}=2(347)-254-422+0.2[2(347)-254-422]=20 \\
& M_{x p}=2(458)-646+0.2[2(458)-2(449)]=274 \\
& M_{\mathrm{Xq}}=2(646)-458-551+0.2[2(646)-2(614)]=296 \\
& M_{X r}=2(551)-646-385+0.2[2(551)-2(476)]=101 \text { " } \\
& \mathrm{M}_{\mathrm{Xs}}=2(385)-551-422+0.2[2(385)-2(254)]=-151 \quad \text { " } \\
& \mathrm{M}_{\mathrm{xt}}=2(422)-385-473+0.2[2(422)-2(347)]=16 \quad \text { " } \\
& M_{X u}=2(473)-2(422)+0.2[2(473)-2(422)]=122
\end{aligned}
$$

The My moments at the mesh points are:


## CHAPTER 5

## DISCUSSION OF RESUIRS AND CONCLUSION

5.1. Static Ioad Check.


Fig. 4.15. One-half of an interiot panel.
Let (Fig. 4.15) represent one-half of an interior panel. If this was a real intermediate panel that is to say an infinite number of panels extended in both directions, then the shear along the lines $A B, B D$, and $C D$ will be zero. Therefore the sum of moments along $B D$ and AC must be aq ${ }^{2}$ where $a=1 / 8$, no matter what the distribution of moments along this line would be. The sum of moments along AEC will be the area of the moment diagram.


Fig. 4.16. Moment diagram along AEC.
$\left.\frac{(746+290}{2}\right)(0.5)(2)=\frac{1036}{2}(0.5)(2)=518 \mathrm{~kg}-\mathrm{m}$.

$$
\frac{(290+151)}{2}(0.5)(2)=\frac{441}{2}(0.5)(2)=\frac{220}{738} \quad . \quad .
$$

The sum of moments along $B D$ is.


Fig. 4.17. Moment diagram along BD. $\frac{(221+147)}{2}(0.5)(2)=\frac{368}{2}(0.5)(2)=184 \mathrm{~kg}-\mathrm{m}$. $\frac{(147+122)}{2}(0.5)(2)=\frac{269}{2}(0.5)(2)=\frac{135}{319} \quad$ "

The sum of moments along $A E C$ and $B D$ are $=738+319=1057 \mathrm{kgm}$. The load on the $2 \mathrm{~m}_{.}$slab is, $q=1000 \mathrm{~kg} \cdot / \mathrm{m}^{2} .\left(2 \mathrm{~m}_{\bullet}\right)=2000 \mathrm{~kg} . / \mathrm{m}_{0}$ $M=\frac{1}{8} q l^{2}=\frac{1}{8}(2000)\left(2^{2}\right)=1000 \mathrm{~kg} \cdot \mathrm{~m}$.

The sum of moments of 1057 found by relaxation and the moment of the static load are in good proxmity for statical comparison.

Next we shall find out what percentage of this total moment goes to negative and positive moments. It is observed that of this 1057 total moment,

$$
\frac{738}{1057}=0.70=70 \% \text { goes to negative moment. }
$$

and $\quad \frac{319}{7057}=0 \cdot 30=30 \%$ goes to positive moment. $\overline{1057}$

The slab under investigation shall be divided into strips. The strips of interest in the thesis shall be the column strip and the midde strip. These strips are shown in (Fig. 4.18). Of the total negative moments, $\frac{-746-290-290}{3}=\frac{-1326}{3}=-441 \mathrm{~kg}-\mathrm{m}$, is the moment for the column strip. $\frac{-290-151-290}{3}=\frac{-243}{3}=\frac{-243}{-684} \because$ is the moment $\because$ for the middle strip.
$\frac{441}{684}=0.645=64.5 \%$ is the percentage of the negative moment at the colum strip.
$243=0.355=35.5 \%$ is the percentage of the negative moment 684 at the middle strip.
of the total positive moments, $\frac{+147+221+147}{3}=\frac{515}{3}=+172$ is the moment for the column strip. $\frac{+147+122+147}{3}=\frac{416}{3}=+139$ is the moment for the middle strip. $\frac{172}{311}=0.55=55 \%$ is the percentage of the positive moment at the column stria $\frac{139}{311}=0.45=45 \%$ is the percentage of the positive moment at the middle stri


Fig. 4.18. The middle and column strips of a panel $l_{A}^{0}$ with a column at E.

The results obtained shall be put in tabular form.

## TABLE FIVE

PERCENTAGE OF MOMENTS BETWEEN COLUMN STRIPS AND MIDDLE
STRIPS IN PERCENT OF TOTAL MOMENTS AT CRITICAL SECTIONS OF A PANEL O.

| Strip | Moment Section |  |
| :---: | :---: | :---: |
|  | Negative Moment |  |
|  | Positive |  |
| Moment |  |  |$|$

The slab analyzed above shall be compared by the elastic analysis method of the ACI Code. In design by elastic analysis several assumptions are made.*

Journal of ACI. Feb. 1962, proc. v.59, No.2; P. 229-231, Table 2103(c).
a) Assumptions:

1. The structure may be considered divided into a number of bents, each consisting of a row of columns or supports and strips of supported slabs, each strip bounded laterally by the center line of the panel on either side of the center line of columns or supports. The bents shall be faken longitudinally and transversely of the building.
2. Each such bent may be analyzed in its entirety; or each floor thereof and the roof may be analyzed seperately with its adjacent columns as they occur above and below, the columns beeing assumed fixed at their remote ends. Where slabs are thus analyzed separately, it may be assumed in determining the bending at a given support that the slab is fixed at any support two panels distant therefrom provided the slab continues beyond that point.
3. The joints between columns and slabs may be considered rigid, and this rigidity (infinite moment of inertia) may be assumed to extend in the slabs from the center of the columns to the edge of the capital, and in the column from the top of the slab to the bottom of the capital. The change in length of columns and slabs due to direct stress, and deflections due to shear, may be neglected.
4. Where metal column capitals are used, account may be taken of their contributions to stiffness and resistance to bending and she
5. The moment of inertia of the slab or column at any cross section may be assumed to be that of thefcross section of the concrete妾See item No: 6 in bibliography.

Variation in the moments of inettia of the slabs and columns along their axes shall be taken into account.
6. Where the load to be supported is definitely known, the structure shall be analyzed for that load. Where the live load is variable but does not exceed three-quarters of the dead load, or the nature of the live load is such that ail panels will be loaded simultaneously, the maximum bending may be assumed to occur at all sections under full live load. For other conditions, maǐimum positive bending near midspan of a panel may be assumed to occur under three-quarters of the full live load in the panel and in alternate panels; and maximum negative bending in the slab at a support may be assumed to occur under three-quarters of the full live load in the adjacent panels only. In no case, shall the design moments be taken as less that those occuringtwith full live load on all panels. b) Gitical Sections:

The critical section for negative bending, in both the column strip and middle strip, may be assumed as not more than the distance A from the center of the column or support and the critical negative moment shall be taken to consideration as extending over this distance
c) Distribution of Panel moments:

Bending at critical sections across the slabs of each bent may be apportined between the column strip and middle strip, as given in Table Six. For design purposes, any of these percentages may be varied by not more than $10 \%$ of its value, but their sum for the full panel width shall not be reduced.

## TABLE SIX

PERCENTAGE OF MOMENTS BETWEEN COLUMN STRIPS AND IIIDDLE
STRIPS IN PERCENI OF TOTAL MONENTS AT CRITICAI SECTIONS OF A PANEL

|  | Moment Section |  |
| :---: | :---: | :---: |
| Strip | Negative Moment <br> at Interior Support | Positive <br> Moment |
| Column Strip | 76 | 60 |
| Middle Strip | 24 | 40 |

5.2. Conclusion. It is seen that the values in Tables Five and Table Six are quite close so that the elastic analysis proposed by the ACI Code agrees well with the theoretical analysis. However, as it is seen, the relaxation method is easily applicable specially in cases where the elastic analysis proposed by the ACI Code may give questionable results such as a column in the middle of a slab or. slabs with unusual loadings.

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Fig. 4.19. A square net with nodes indicated.
In terms of the $w$ values at the nodes of a square net as indicated in (Fig. 4.19), the following finite-difference approximations to low-order derivatives are frequently neededand have been collected together here for ease of reference:

First Derivatives

$$
\begin{aligned}
& \left(\frac{\partial w}{\partial x}\right)_{0}=\frac{w 7-w z}{2 h} \\
& \left(\frac{\partial w}{\partial y}\right)_{0}=\frac{w 2-w 3}{2 h}
\end{aligned}
$$

Second Derivatives

$$
\left(\frac{\partial^{2} w}{\partial x^{2}}\right)_{0}=\frac{w 7+w 3-2 w 0}{h^{2}},
$$

$$
\left(\frac{\partial^{2} w}{\partial y^{2}}\right)_{0}=\frac{w 2+w 4-2 w a}{h^{2}}
$$

$$
\left(\nabla^{2} w\right)_{0}=\frac{w+w 2+w 3+w 4-4 w_{0}}{h^{2}}
$$

$$
\left(\frac{\partial^{2} w}{\partial x \partial y}\right)_{0}=\frac{w 5-w 6+w 7-w 8}{4 h^{2}}
$$

Third Derivatives

$$
\begin{aligned}
& \left(\frac{\partial^{3} w}{\partial x^{3}}\right)_{0}=\frac{w^{-2 w 1+2 w 3-w 11}}{2 h^{3}} \\
& \left(\frac{\partial^{3} w}{\partial y^{3}}\right)_{0}=\frac{w-2 w 2+2 w 4-w 12}{2 h^{3}}
\end{aligned}
$$

Fourth Derivatives

$$
\begin{aligned}
&\left(\frac{\partial^{4} w}{\partial x^{4}}\right)_{0}=\frac{6 w-4 w 1-4 w 3+w 9+w 11}{h^{4}}, \\
&\left(\frac{\partial^{4} w}{\partial y^{4}}\right)_{0}=\frac{6 w 0-4 w 2-4 w 4+w 20+w 12}{h^{4}}, \\
&\left(\frac{\nabla^{4} w}{}\right)_{0}=\frac{20 w 0-8(w 7+w 2+w 3+w 4)+2(w 5+w 6+w 7+w 8)}{h^{4}}+ \\
&+\frac{(w 9+w 10+w 71+w 12)}{h^{4}} \\
&\left(\frac{\partial^{4} w}{\partial x^{2} y^{2}}\right)_{0}=\frac{4 w_{0}-2\left(w 7+w 2+w 3+w^{4}\right)+(w 5+w 6+w 7+w 8)}{h^{4}},
\end{aligned}
$$

